

# *Algorithmic Challenges in Multiscale Quantum Simulation of Strongly-Correlated Materials*

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Libraries and Algorithms for Petascale Applications

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## Next Generation Multi-Scale Quantum Simulation Software for Strongly Correlated Materials

<http://scicompforge.org/petamat>

- SciDAC senior personnel
  - University of Cincinnati
    - Mark S. Jarrell, Physics (PI)
    - Karen Tomko, Electrical and Computer Engineering
  - Oak Ridge National Laboratory
    - Thomas A. Maier, Physics (co-PI)
    - Eduardo F. D'Azevedo, Computer Science and Mathematics
  - University of California at Davis
    - Zhaojun Bai, Computer Science (co-PI)
    - Sergey Y. Savrasov, Physics
    - Richard T. Scalettar, Physics

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## Modeling Materials at Petascale

- **Study of Strongly-Correlated Materials;**
  - Great technological promises.
    - most magnets and superconductors fall into this category.
  - Poorly understood.
    - properties of the materials are determined by complex interaction of electrons  
long-ranged spin and charge correlations, competing ground states, complex phase diagrams, etc.
- **Goals of the project;**
  - **Numeric:** develop mathematical and numerical understanding of the model.
  - **Algorithmic:** develop massively parallel multi-scale method with a simple user interface.
  - **Scientific:** better understand their properties to improve and create new materials.
- **Multiscale modeling**
  - **Short-length scales:** 10 – 100 electrons with **QMC methods**.
  - **Intermediate-length scales:** 100 – 1, 000 electrons using vertices from QMC.
  - **Long-length scales:** 1, 000 – electrons with mean field approximation.

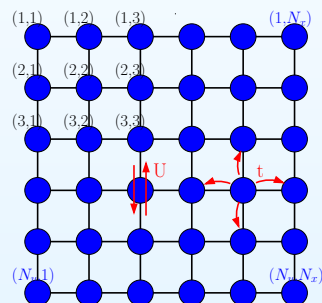
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## Hubbard model

- **Hubbard Hamiltonian** captures the exact correlation of neighboring electrons,

$$\mathcal{H} = \mathcal{H}_U + \mathcal{H}_t + \mathcal{H}_\mu,$$

- potential energy  $U$ , kinetic energy  $t$ , and chemical energy  $\mu$  of electrons.
- **Study of the electron interactions on 2D lattice:**



- Number of lattice sites  $N = N_x \times N_y$ 
  - $N_x$  sites in  $x$  direction and  $N_y$  sites in  $y$  direction.
  - one electron per site on average, i.e.,  $\mu = 0$ .
- Discretize inverse temperature  $\beta$  into  $L$  intervals.

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## Computational kernel

Computational kernel of QMC simulation solves

$$Ax = b,$$

where  $A = M^T M$  is SPD and

$$M = \begin{pmatrix} I & & & B_1 \\ -B_2 & I & & \\ & \ddots & \ddots & \\ & & -B_L & I \end{pmatrix}.$$

- Each  $B_l \in \mathcal{R}^{N \times N}$  is defined as

$$B_l = e^{t\Delta\tau K} e^{\nu V_l}$$

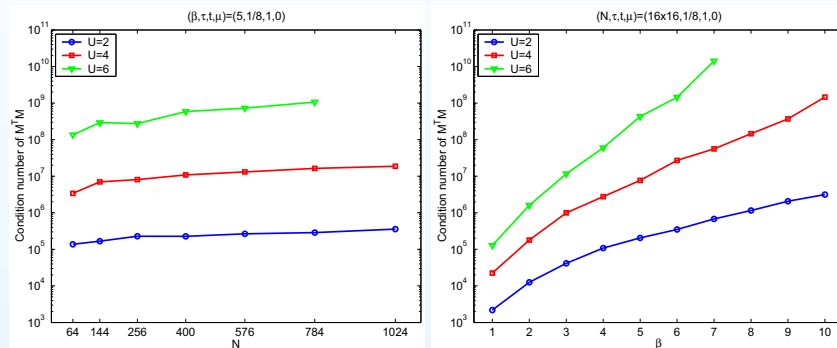
where

- $K \in \mathcal{R}^{N \times N}$  describes the lattice structure and stays same through simulation,
- $V_l = \text{diag}(h_{l,1}, h_{l,2}, \dots, h_{l,N})$  is random config. and changes for each solution,
- $\Delta\tau = \beta/L$  is a discretization parameter, and  $\nu$  is defined as  $\cosh \nu = e^{\frac{U\Delta\tau}{2}}$ .

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## Computational bottleneck

- Large and ill-conditioned system;
  - $N = \mathcal{O}(10^3)$ ,  $L = \mathcal{O}(10^2)$ , and  $NL = \mathcal{O}(10^5)$ .
  - Conditioning of the matrix changes with the parameters.

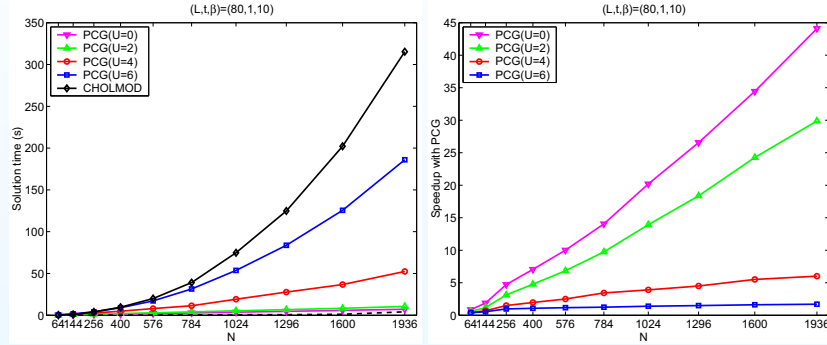


- The linear solver accounts for 80% - 90% of the total simulation time.
  - a large number of solutions are required for each simulation with different  $V_l$ .
  - $A$  is large but sparse and structured:
    - matrix-vector multiply in matrix-free form with  $\mathcal{O}(NL)$ -computation.
  - high-accuracy is not required for each solution.

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## Linear solver

- Comparison of PCG with Tim Davis' CHOLMOD in UMFPACK.



- Specialized direct solver with block-cyclic reduction;
  - dense  $N \times N$  matrix operations;
    - matrix-matrix multiply and QR factorization.
  - $\mathcal{O}(N^3)$ -computational complexity.
  - $\mathcal{O}(N^2 L)$ -storage requirement.
- Toward “optimal”  $\mathcal{O}(N)$ -complexity.
  - My research focuses on preconditioning techniques.

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## New preconditioning technique

The preconditioner  $R$  is constructed based on the factorization of the form

$$A + \alpha \cdot D_A = RR^T + E,$$

where  $R$  is lower-triangular, and  $E$  is a symmetric error matrix. By combining

1. the static diagonal shifting of  $A$  with a scalar  $\alpha$ , and
2. the dynamic updating of  $E = RF^T + FR^T - S - S^T$ ;
  - $F$  and  $S$  are strictly-lower triangular,
  - two-levels of drop tolerance  $\sigma_1$  and  $\sigma_2$  such that  $\|F\| \leq \sigma_1$ ,  $\|S\| \leq \sigma_2$ , and

$$\sigma_1 \geq \sigma_2 = \alpha,$$

we can control the magnitude of entries in the residual matrix

$$I - R^{-T}AR^{-1} = \underbrace{F^T R^{-1} + R^{-1}F}_{\#1} - \underbrace{R^{-1}(S + \alpha D_A + S^T)R^{-T}}_{\#2},$$

where small enough  $\sigma_2$  to make #1 dominant results in an efficient yet high-quality  $R$ .

- Related works: [Manteuffel'80] [Kaporin'98]

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## New sparse data structure

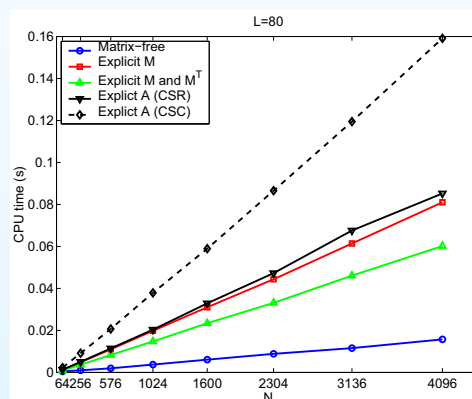
- Extended Compressed Sparse Column (ECSC) format;

$$\underbrace{valR, rowR, ptrR}_{\text{CSC}} \quad \underbrace{linkR, headR}_{\text{Row Access}} \quad \underbrace{nextF}_{\text{Access } F}$$

- avoids the storage of and operations with zero elements.
  - accommodates all the underlying access pattern.
  - never updates the data structure once non-zeros are stored.
  - increases the storage requirement by 70% from CSC format.
    - both  $R$  and  $F$  are sparse enough.
  - exploits memory hierarchy, but only for column-access.
- Note: for each solution, sparsity pattern is same for  $A$  but not for  $R$ .

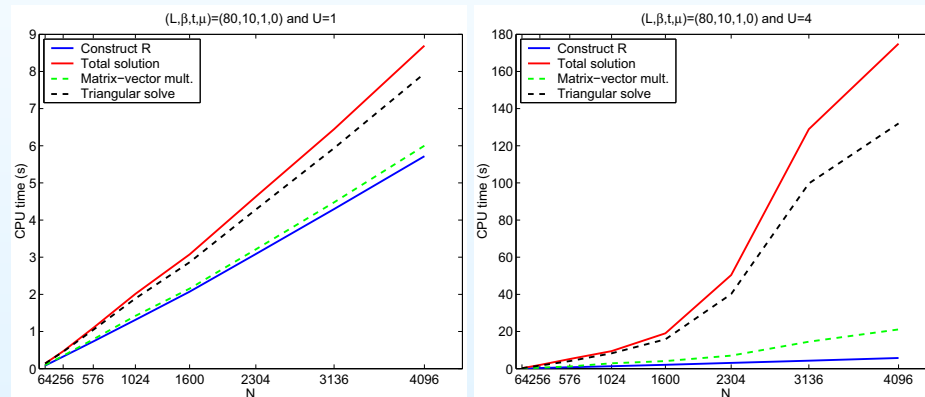
## Sparse matrix-vector multiply

- Optimizing matrix-vector multiply with explicitly-stored matrix
  - same sparsity pattern of  $A$  for all solutions, but
  - the matrix-vector multiply is more efficient in matrix-free form for PCG iterations.



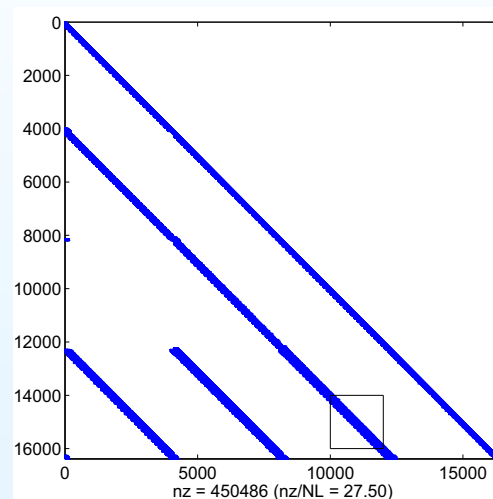
## PCG bottleneck

- Matrix-vector product can be computed efficiently in a matrix-free form.
- Sparse triangular solve is the bottleneck.
  - $R$  is stored in MSC format and applied with register-level tuning.



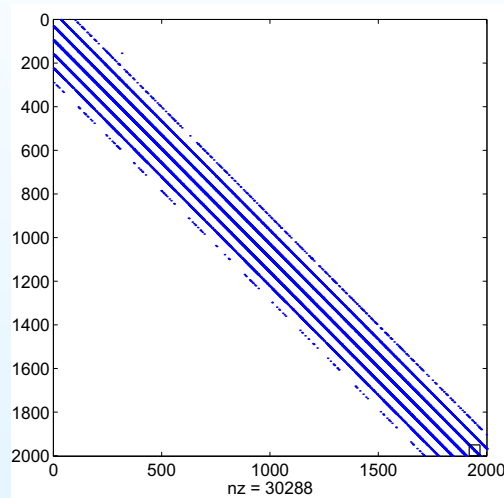
## Sparse triangular solve

- Sparsity pattern of  $R$ , i.e., large and sparse blocks.
  - $R$  with  $(N, L) = (64 \times 64, 4)$ .



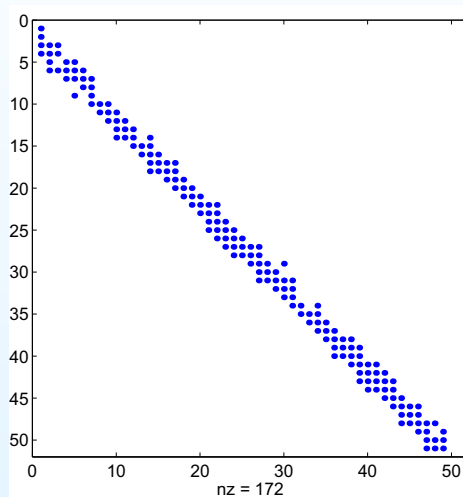
## Sparse triangular solve

- Sparsity pattern of  $R$ , i.e., large and sparse blocks.
  - $R(14000 : 16000, 10000 : 12000)$  with  $(N, L) = (64 \times 64, 4)$ .



## Sparse triangular solve

- Sparsity pattern of  $R$ , i.e., large and sparse blocks.
  - $R(15950 : 16000, 11920 : 11970)$  with  $(N, L) = (64 \times 64, 4)$ .



- Sparse optimization techniques like OSKI by BeBOP did not work.